

**M.Tech I Semester Regular & Supplementary Examinations January/February 2019**  
**SOLID STATE DC DRIVES**

(Common to PE, PID, PEED and PED)  
(For students admitted in 2017 & 2018 only)

Time: 3 hours

Max. Marks: 60

Answer all the questions

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- 1 (a) Explain Ward-Leonard speed control of dc motor.  
(b) Briefly explain how the rating of a motor is selected.  
**OR**
- 2 The speed of a 10 HP, 230 V, 1200 rpm separately excited dc motor is controlled by a single phase full converter. The rated motor armature current is 38A and the armature resistance is  $0.3\Omega$ . The ac supply voltage is 260 V. The motor voltage constant is  $K_a \Phi = 0.182 \text{ V/rpm}$ . Assume that sufficient inductance is present in the armature circuit to make the motor current continuous and ripple free.  
Rectifier operation (Motoring Action): for a firing angle  $\alpha = 30^\circ$  and rated motor current calculate:  
(i) The motor torque. (ii) The speed of the motor. (iii) The supply power factor  
Inverter operation (Regenerating Action) The polarity of the motor back emf  $E_b$  is reversed by reversing the field excitation. Calculate  
(i) The firing angle to keep the motor current at its rated value  
(ii) The power fed back to the supply
- 3 Explain the working of a single phase semi converter fed dc drive with wave forms and basic equations. <http://www.jntuonline.com>  
**OR**
- 4 Explain the operation of three phase dual converter fed DC drives
- 5 What is a multiphase chopper? Bring out clearly with appropriate waveforms the difference between the in-phase operation and phase shifted operation of a multiphase chopper. Also explain why is phase shifted operation always preferred.  
**OR**
- 6 Explain in detail dynamic braking of dc motor using chopper.
- 7 The speed of a separately excited dc motor is controlled by a chopper. The dc supply voltage is 120 V, armature circuit resistance is  $0.5 \Omega$ , and armature circuit inductance is 20mH and motor constant is  $K_a \Phi = 0.05 \text{ V/rpm}$ . The motor drives a constant torque load requiring an average armature current of 20A. Assume that motor current is continuous.  
Determine: (i) The range of speed control. (ii) The range of duty cycle  $\alpha$ .  
**OR**
- 8 Explain in detail the design of current controller of closed loop control system of separately excited DC motor.
- 9 Draw and explain the program flow chart for constant horse power and load distributed operations.  
**OR**
- 10 Explain in detail about micro computer control of DC drives.

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